CHAPTER 1
Fundamentals of Distributed System

➢ INTRODUCTION

➢ DISTRIBUTED COMPUTING MODELS

➢ SOFTWARE CONCEPTS

➢ ISSUES IN DESIGNING DISTRIBUTED SYSTEM

➢ CLIENT – SERVER MODEL
What is a Distributed System?

Tanenbaum’s definition of a distributed system:

“A distributed system is a collection of independent computers that appear to the users of the system as a single coherent system.”
An Example of a Distributed System

- Nationalized Bank with multiple Branch Offices
Requirements of Distributed Systems

- Security and reliability
- Consistency of replicated data
- Concurrent transactions (operations which involve accounts in different banks; simultaneous access from several users, etc.)
- Fault tolerance
Architectures for Distributed Systems

• Shared memory architectures / Tightly coupled systems
  ➢ easier to program

• Distributed memory architectures / Loosely coupled systems
  ➢ offer a superior price performance ratio and are scalable
Architectures for Distributed Systems

Shared memory architecture

Distributed memory architecture

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Distributed Computing Models

- Workstation model
- Workstation–server model
- Processor-pool model
Workstation Model

- Consists of network of personal computers
- Each one with its own hard disk and local file system
- Interconnected over the network
Workstation-server Model

• Consists of multiple workstations coupled with powerful servers with extra hardware to store the file systems and other software like databases
Processor-pool Model

- Consists of multiple processors: a pool of processors and a group of workstations
Advantages of Distributed Systems

- Inherently distributed applications
- Information sharing among geographically distributed users
- Resource Sharing
- Better price performance ratio
- Shorter response time & higher throughput
- Higher reliability and availability against component failures
- Extensibility and Incremental Growth
- Better Flexibility
Disadvantages of Distributed Systems

• Relevant software does not exist currently

• Security poses a problem due to easy access to all data

• Networking saturation may cause a hurdle in data transfer
Software Concepts

- Network Operating System (NOS)
- Distributed Operating System (DOS)
- Multiprocessor Time Sharing System
Network Operating System (NOS)

• Build using a distributed system from a network of workstations connected by high speed network.
• Each workstation is an independent computer with its own operating system, memory and other resources like hard disks, file system and databases.
Distributed Operating System (DOS)

• Enables a distributed system to behave like a virtual uniprocessor even though the system operates on a collection of machines.

• Characteristics
  ✓ enabling Inter process communication
  ✓ Uniform process management mechanism
  ✓ Uniform and visible file system
  ✓ Identical kernel implementation
  ✓ Local control of machines
  ✓ handling scheduling issues
Multiprocessor Time Sharing System

- Combination of tightly coupled software and tightly coupled hardware with multiple CPUs projecting a uniprocessor image.
- Tasks are queued in shared memory and are scheduled to be executed in time shared mode on available processors.
## Comparison of Different Operating Systems

### Software Concepts

<table>
<thead>
<tr>
<th>Criteria</th>
<th>Network OS</th>
<th>Distributed OS</th>
<th>Multiprocessor time-sharing OS</th>
</tr>
</thead>
<tbody>
<tr>
<td>Projects a virtual uniprocessor image</td>
<td>No</td>
<td>Yes</td>
<td>Yes</td>
</tr>
<tr>
<td>Runs same operating system</td>
<td>No</td>
<td>Yes</td>
<td>Yes</td>
</tr>
<tr>
<td>Copies of operating system</td>
<td>N</td>
<td>N</td>
<td>1</td>
</tr>
<tr>
<td>Access to files</td>
<td>Sharing</td>
<td>Messages in memory</td>
<td>Sharing</td>
</tr>
<tr>
<td>Network protocols required</td>
<td>Yes</td>
<td>Yes</td>
<td>No</td>
</tr>
<tr>
<td>Single run queue</td>
<td>No</td>
<td>No</td>
<td>Yes</td>
</tr>
<tr>
<td>Well-defined file sharing</td>
<td>Usually no</td>
<td>Yes</td>
<td>Yes</td>
</tr>
</tbody>
</table>

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Issues in Designing Distributed Systems

- Transparency
- Flexibility
- Reliability
- Performance
- Scalability
- Security
## Transparency

Transparencies required for Distributed Systems

### Types of transparencies

<table>
<thead>
<tr>
<th>Transparency</th>
<th>Description</th>
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</thead>
<tbody>
<tr>
<td>Access</td>
<td>Hide the differences in data representation and how a resource is accessed</td>
</tr>
<tr>
<td>Location</td>
<td>Hide where a resource is physically located</td>
</tr>
<tr>
<td>Migration</td>
<td>Hide the movement of a resource to another location</td>
</tr>
<tr>
<td>Relocation</td>
<td>Hide the movement of a resource to another location while in use</td>
</tr>
<tr>
<td>Replication</td>
<td>Hide the fact that multiple copies of the resource exist without user’s knowledge</td>
</tr>
<tr>
<td>Concurrency</td>
<td>Hide the fact that a resource may be shared by several users</td>
</tr>
<tr>
<td>Failure</td>
<td>Hide the failure and recovery of a resource</td>
</tr>
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<td>Persistence</td>
<td>Hide whether a resource is in memory or on disk</td>
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</table>
Replication Transparency

Locating Replicated File stored on any server

Location transparency
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Flexibility

• Monolithic kernel approach
• Here kernel does all functions and provides facilities at local machine
• There is over Burdon on kernel

• Microkernel approach
• It takeout as much functionality as possible from kernel And retain only essential functions.
• Provides only few functions in the kernel while uses process server to manage IPC,pager fro MM and fs management.
• Its easy to port maintain and extend
flexibility

• In initial stages there may be need for modification of platform
• The best way to achieve flexibility is to take a decision where to use monolithic or microkernel on each machine.
• Kernel is the central controller which provides basic system facilities.
Monolithic Kernel Approach

- Uses the minimalist, modular approach with accessibility to other services as needed
Microkernel Approach

- Uses the kernel does it all approach with all functionalities provided by the kernel irrespective whether all machines use it or not
Monolithic versus Microkernel Approach

Monolithic vs microkernel

Services (file, network)
Kernel code and data
Reliability

• Availability in case of Hardware failure
• Data recovery in case of Data failure
• Maintain consistency in case of replicated data
Performance

Metrics are

- Response time
- Throughput
- System utilization
- Amount of network capacity used
Scalability

• Techniques to handle scalability issues
  • hide communication latencies
  • hide distribution
  • hide replication

<table>
<thead>
<tr>
<th>Concept</th>
<th>Example</th>
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<tr>
<td>Centralized services</td>
<td>A single server for all users</td>
</tr>
<tr>
<td>Centralized data</td>
<td>A single on-line telephone book</td>
</tr>
<tr>
<td>Centralized algorithms</td>
<td>A single algorithm doing routing based on available information</td>
</tr>
</tbody>
</table>
Hide Communication Latencies

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Hide Distribution

Internet DNS

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Security

- Confidentiality means protection against unauthorized access

- Integrity implies protection of data against corruption

- Availability means protection against failure always accessible
Client-Server Model

The client-server model

The client-server interaction

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Client-Server Addressing Techniques

- Machine addressing
- Process addressing
- Name server addressing
Client-Server Addressing Techniques

(a) Machine addressing
1: Request to client
2: Reply to server

(b) Process addressing
1: Broadcast
2: Give own location
3: Request
4: Reply

(c) Name server technique
1: Lookup in name server
2: Reply from NS
3: Request
4: Reply

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Client-Server Implementation

Messages for client server interaction
- Request, Reply, Acknowledge, Are you Alive, I am Alive

(a) The client–server system uses a Request–Reply protocol with no acknowledgement.

(b) Each packet is acknowledged separately.

(c) A reply is sent as acknowledgment so the number of packets is reduced.

(d) The client checks if the server is still alive and on the network.
Differentiation between the Client and the Server

- User interface level
- Processing level
- Data level

Three-tiered Internet search engine

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Client-Server Architecture

Multi-tiered client-server architecture

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Client-Server Architecture

Server acts as a client
Thank you
PROCEDURAL PROGRAMMING

Procedural programming is by far the most common form of programming. A program is a series of instructions which operate on variables. It is also known as imperative programming.

- Examples of procedural programming languages include FORTRAN, ALGOL, Pascal, C, MODULA2, Ada, BASIC. Despite their differences they all share the common characteristics of procedural programming.

Advantages of procedural programming include its relative simplicity, and ease of implementation of compilers and interpreters.

Disadvantages of procedural programming include the difficulties of reasoning about programs and to some degree difficulty of parallelization. Procedural programming tends to be relatively low level compared to some other paradigms, and as a result can be very much less productive.
Object oriented programming is characterized by the defining of classes of objects, and their properties. Inheritance of properties is one way of reducing the amount of programming, and provision of class libraries in the programming environment can also reduce the effort required. The most widely used object oriented language is C++ which provides object extensions to C, but this is rapidly being overtaken by Java.

Features Of Object-Oriented Programming

Data Abstraction and Encapsulation

Operations on the data are considered to be part of the data type. We can understand and use a data type without knowing all of its implementation details. Neither how the data is represented nor how the operations are implemented. We just need to know the interface (or method headers) – how to “communicate” with the object. Compare to functional abstraction with methods.
Inheritance
Properties of a data type can be passed down to a sub-type – we can build new types from old ones. We can build class hierarchies with many levels of inheritance.

Polymorphism
Operations used with a variable are based on the class of the object being accessed, not the class of the variable. Parent type and sub-type objects can be accessed in a consistent way.

OOP’s world
Class
{  
  Objects
}

Procedural Language world
| structure
{  
  structure variables
  
}
Distributed System and Middleware Concepts
DISTRIBUTED SYSTEM

A distributed system is a collection of independent computers that appears to its users as a single coherent system.

Important characteristics of distributed systems

- Differences between the various computers and the ways in which they communicate are hidden from users.
- Users and applications can interact with a distributed system in a consistent and uniform way, regardless of where and when interaction takes place.

Goals of Distributed System

4 important goals that should be met to make building a distributed system worth the effort they are:

1) Easily connect Users to resources, hide the fact that resources are distributed across a network, open, scalable.
2) **Transparency**

A distributed system that is able to present itself to users and applications as if it were only a single computer system is said to be transparent. Which hides whether a implementation i.e. software resource is in main memory or disk.

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3) Openness

An open distributed system is a system that offers services according to standard rules.

4) Scalability

Scalability of a system can be measured along at least three different dimensions:
- First, a system can be scalable with respect to its size, we can easily add more users and resources to the system.
- Second, a geographically scalable system users and resources may lie far apart.
- Third, a system can be administratively scalable; it can still be easy to manage even if it spans many independent administrative organizations.
Reference

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• ANY QUESTION
THANK YOU